Parallel implementation

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Covered in this lecture:

- Compiling the code.
- Running the code.
- Optimizing parallel model implementations.
  - Parallel implementation of individual grids (*ww3_shel*).
  - Additional options in *ww3_multi*.
    - Hybrid parallelization.
    - Profiling.
    - Memory use (+IO).
  - Considerations and pitfalls.
  - Future …. 
Parallel implementation of WAVEWATCH III

- Using MPI only, but code (switches) allow for other type of parallel architecture.
  - MPI was the standard before, now is even more so.
  - Thinking about shmem (Cray) style parallel implementation but never had the need to act on this.

- Not all codes use / can benefit from parallel implementation:
  - Actual wave model codes `ww3_shel`, `ww3_multi`, …. will run much more efficient.
  - Initialization code `ww3_strt` may need in some cases for memory use (rarely if ever used at NCEP).
Make sure MPI is implemented correctly:

- Large majority of issues with MPI have been in MPI implementation:
  - Even on our production IBM power series machines.
  - Hope you have good IT support.
Compile in several steps:

- Set switches for serial code (SHRD switch)
- Compile serial codes from scratch:
  - Call `w3_new` to force complete compile of all routines (not strictly necessary).
  - Call `w3_make` with or without program names to get base set of serial codes.
- Set switches for parallel code (DIST and MPI switch).
- Compile parallel codes:
  - Compile selected codes only
    - `w3_make ww3_shel ww3_multi` ....
  - This will automatically recompile all used subroutines.

All this is done automatically in `make_MPI`. 
Running parallel

Running code in parallel depends largely on hardware and software on your computer.

- Generally there is a parallel operations environment:
  - “poe” on IBM systems
  - “mpirun” or other on Linux systems.
  - Sometimes, environment needs to be started separately.
    - `mpdboot` on UMD cluster.
  - Check out with your system, IT support if you have it.
- There are some examples in the test scripts, particularly the `ww3_multi` and real-world test cases `mww3_test_NN` and `mww3_case_NN`.
- Pitfall: many duplicate output lines: you are running a serial code in a parallel environment …..
Optimization

Three things to consider while optimizing the implementation.

- General code optimization (no further discussion):
  - Compiler options.
  - Switches (2\textsuperscript{nd} order versus 3\textsuperscript{rd} order propagation, etc.)
  - Spectral resolution.
  - Time stepping.

- MPI optimization (no further discussion).
  - Often overlooked, but can be very important on Linux systems.

- Application optimization (see below):
  - Cannot do too much with \textit{ww3\_shel}, but will show techniques used here.
  - Many additional options in \textit{ww3\_multi}.

The prognostic variable is the spectral wave energy density as a function of spatial and spectral coordinates and of time.
Propagation:

- By definition linear, nonlinear corrections possible.
- Covers all dimensions.

Physics:

- Wave growth and decay due to external factors:
  - wind-wave interactions,
  - wave-wave interactions,
  - dissipation.
- Local in physical space.
Time splitting / Fractional steps. Separate treatment of:

- physics (local),
- local propagation effects (change of direction or frequency),
- spatial propagation.

Each step consecutively operates on small subsets of data.

Entire model in core, memory requirements less than twice that of storing single state.
Physics involved suggest that grid points are distributed over processors rather than spectral components, particularly for the time splitting and source term integration techniques used in WAVEWATCH III.
Blocking:
- Only data at block bound. needed.
- Total amount of data comm. is a function of # of processes.
- Algorithm depends on actual prop. scheme.

Scattering:
- Full data transpose needed.
- Total amount of data comm. nearly constant.
- Algorithm independent of prop. scheme.
- Load balancing easier.
For WAVEWATCH III (ww3_shel) the scattering method is used because:

- Compatibility with previous versions.
- Maximum flexibility and transparency of code (future physics and numerics developments).
- Feasibility based on estimates of amount of communication needed.
- MPI used for portability.
Standard optimization techniques:

- Non-blocking communication.
- Persistent communication, mainly for transparency of code.

Buffering of the data during transpose:

- Avoids idle CPU cycles during communication operations.
- Communication “hidden” behind calculations.

```
processors with native data

0
1
2
3

gather
scatter

1-D array with given spectral component for all sea points

buffer
active buffer

Corresponding 2-D spatial wave field

calculate propagation

at target processor
```

Version 1.3, Feb. 2013
WW Winter School 2013
Parallel implementation 14/28
Performance test case:

- Global model version with 288 x 157 spatial grid points (30,030 sea points) and 600 spectral components. 12 hour hindcast, 3 day forecast.

Resources:

- IBM RS6000 SP with Winterhawk nodes with 2 processors and 500 Mb memory and a NFS or GPFS file system.
- AIX version 4.3.
- xlf version 6.

Not always applicable to linux ....

MPI setup impact ....
Parallel Efficiency

expected time for ncpu / actual time for ncpu

red: calculation only.
blue: model without output.
green: full model.
dashed and dotted lines: efficiency required to match Cray C90 with 1 or 12 CPUs.
Parallel Efficiency

expected time for ncpu / actual time for ncpu

number of processors (ncpu)

red: calculation only.
blue: model without output.
dashed and dotted lines: efficiency required to match Cray C90 with 1 or 12 CPUs
For mosaic approach, there are other optimization options:

- Splitting grid in overlapping domains:
  - Better local CFL time steps.
  - Hybrid domain decomposition / data transpose.
    ➔ Presently being researched at NCEP.

- Running grids with same rank side-by-side on parts of communicator:
  - Localizing communications.
  - Amdahl's law generally favors running grids side-by-side on smaller number of processors over running in sequence over larger number of processors.
Splitting the communicator:

- Example from mww3_test_03, running three overlapping low resolution grids, with overlay of three overlapping high resolution grids.
  - Example runs low1-3 **serially** on entire communicator.
  - Example runs hgh1-3 **side-by-side** on fractions of communicator.
  - Output can also go to dedicated processors.

```plaintext
from mww3_test_03 ww3_multi input file ..... 

```

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</table>

Note: identical fractions = non-overlapping communicators
### Running with or without output processor

WAVEWATCH III log file  version 4.08
=====================================================================
multi-grid model driver  date : 2013/01/04
time : 11:05:27

. . . . .

Group information :
nr  grids (part of comm.)
-----------------------------------------------
1  1 (0.00-1.00)
2  2 (0.00-0.33)  3 (0.33-0.66)  4 (0.66-1.00)
-----------------------------------------------

Resource assignement (processes) :
grid comp.  grd  pnt  trk  rst  bpt  prt
-----------------------------------------------
low0  001-011  012  ---  ---  ---  ---  ---
hgh1  001-004  012  ---  ---  ---  ---  ---
hgh2  005-007  012  ---  ---  ---  ---  ---
hgh3  008-011  012  ---  ---  ---  ---  ---
-----------------------------------------------
Grid-level profiling:

- Compile under MPI with MPRF switch on.
- Run short piece of model, generating profiling data sets.
- Run GrADS script `profile.gs` to visualize:

  - Example of NCEP’s original multi-grid wave model on next slide.
    - 8 grids.
    - 360 processors.
    - Dedicated I/O processors.
NCEP “multi_1” global model on IBM ca. 2008
Memory use + IO

When running a grid on NAPROC processors, each processor stores:

- NSEA/NAPROC spectra. (scaling)
- Output fields:
  - Version 4.08 and earlier full fields. (not sc.)
  - Version 4.09 and later:
    - Sparse output fields (NSEA/NAPROC). (scaling)
    - Full output fields (NSEA) in 1 processor only, only fields for selected output. (not sc.)
- Other outputs:
  - Gathered in one processor, with some buffering to limit local memory use. (“scaling”)
- Work arrays, interpolation tables, … (not sc.)
### IO consideraions: IO server type IOSTYP in *ww3_shel* and *ww3_multi*.

- **0**: No IO server process, use direct access write in restart file. Requires full parallel file system.
- **1**: No IO server process, each output in single process.
- **2**: Single dedicated IO process for all output.
- **3**: Dedicated IO process for each separate IO type.

In *ww3_multi*, all point output can go to dedicated processor.

<table>
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</tbody>
</table>
IO considerations:

- Use IO server to manage memory use as well as faster IO.
  - Combine with smart placement on nodes (e.g., less processes on node that does IO) leaves much flexibility for efficient loading of large grids.

- Use overlapping grids:
  - Each grid has much smaller full field arrays.
  - Stitch together later with *ww3_gint*.
Considerations and pitfalls:

- Intra-node and across-node communications are very different.
  - Keeping grid on node may be important.
- Scaling on different systems is very different:
  - IBM-SP versus Linux.
  - Impact of file system.
  - Optimization of MPI.
    - Data transpose is many small messages, MPI needs to be tuned for this …
- For operational models, dimension for worst case:
  - Profile without ice.
  - Consider smallest grids with largest storms in consideration of load balancing.
Optimization future

Working on the following:

- Hybrid domain decomposition / data transpose parallel using *ww3_multi* and automatic grid splitting code (under development).

- Provide some assessment of optimization for both climate (low-res, high-speed), and deterministic (high-res, high-speed) implementations.

Stay tuned!
The end

End of lecture